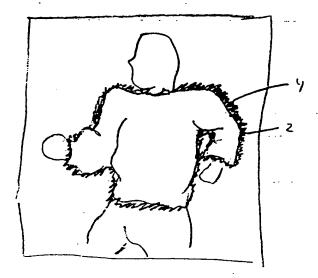
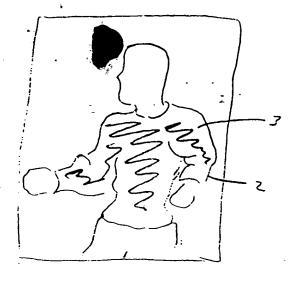


F131A



F, LC



F., 1B

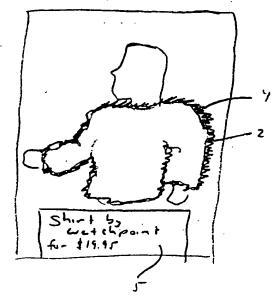
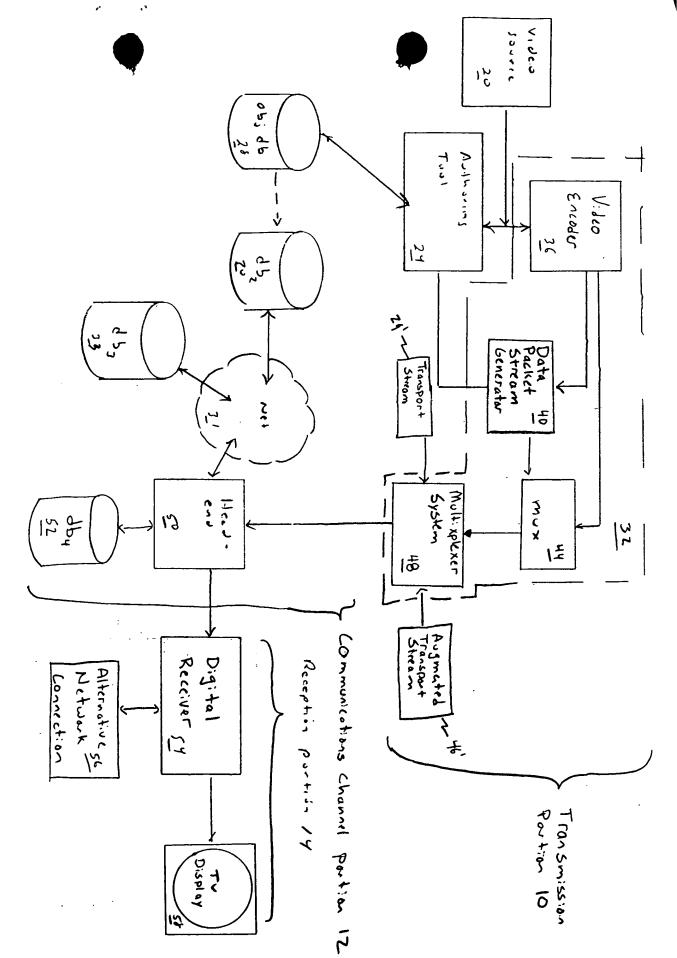
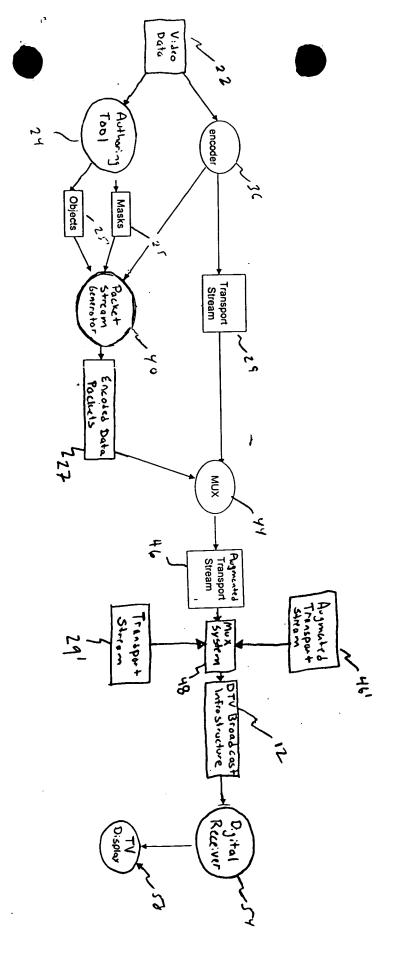


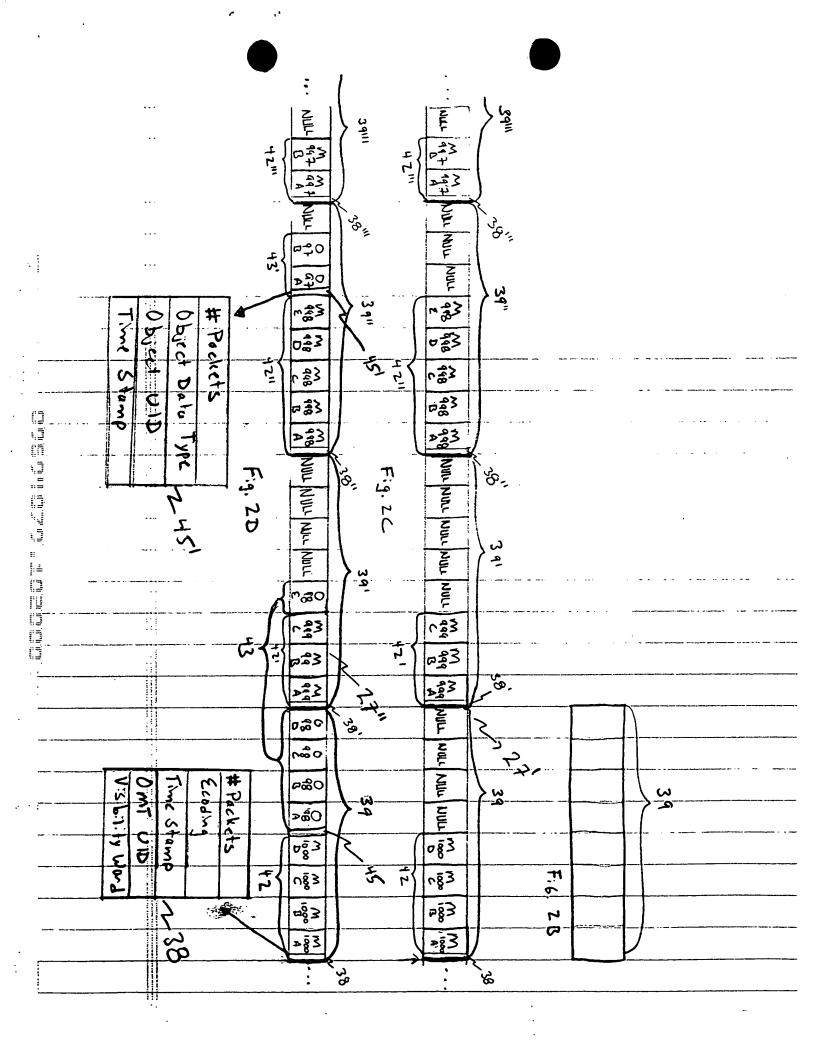
Fig 1D

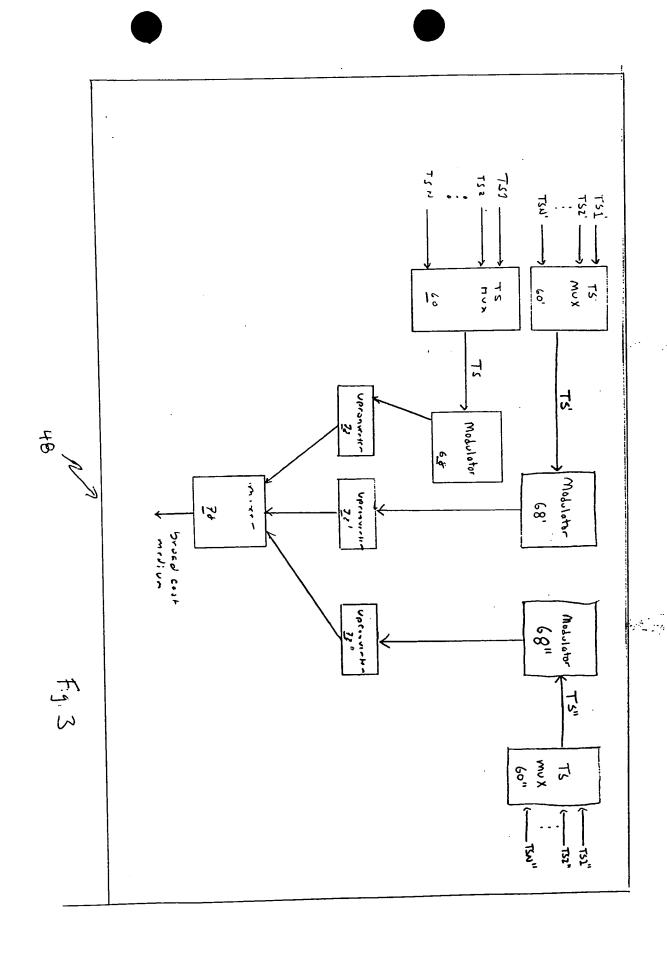


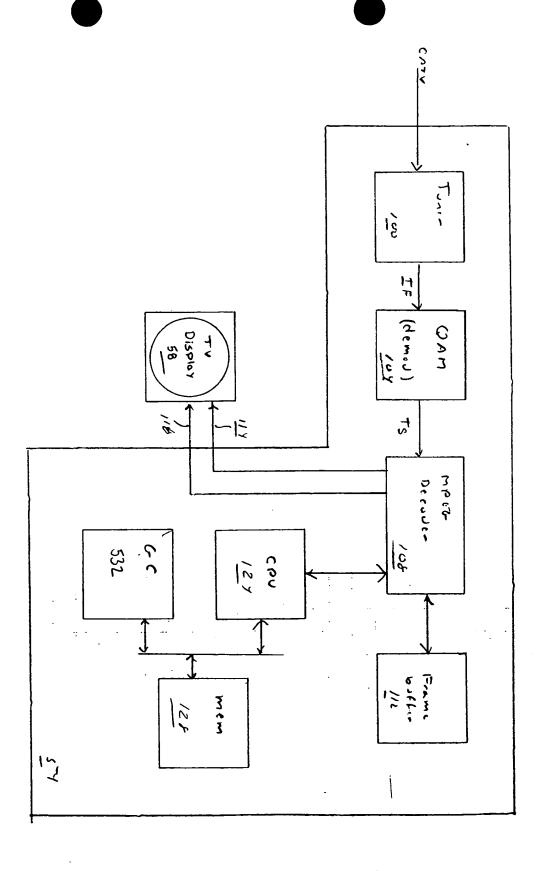
Fis Z

FIS ZA

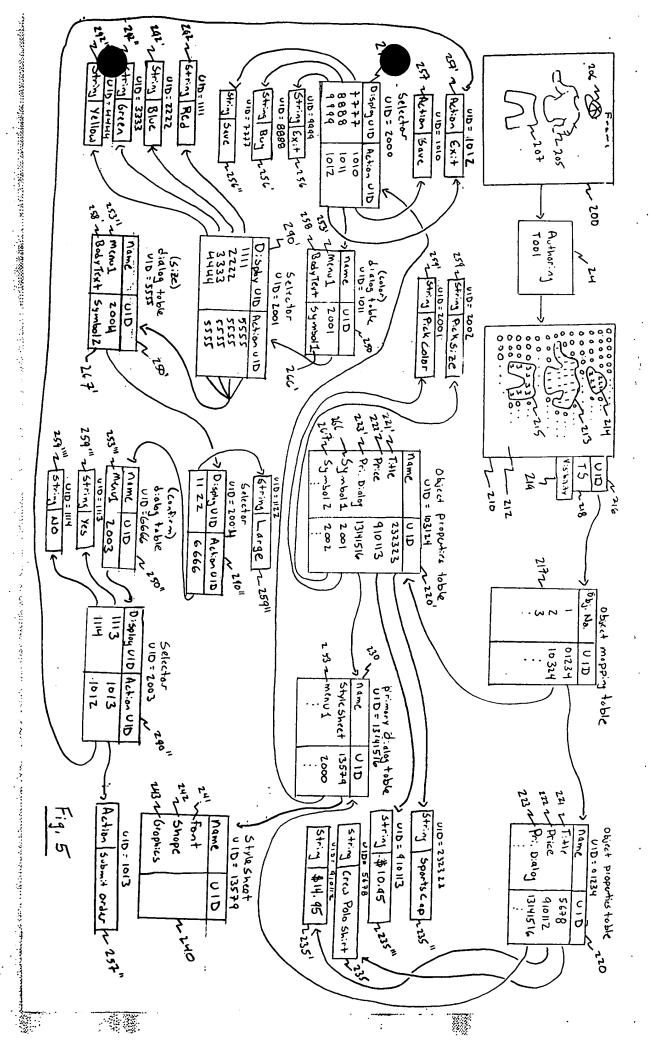


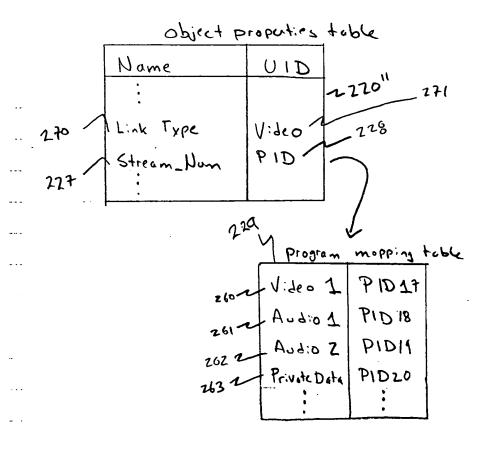




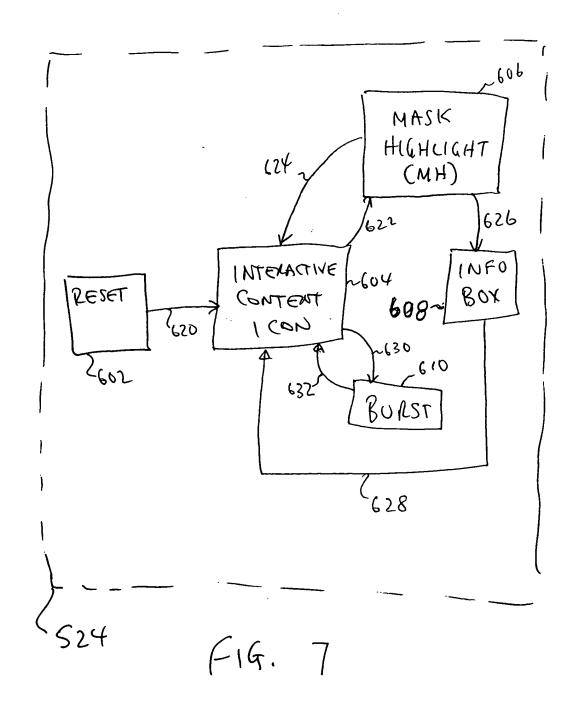


-T -E





Figure





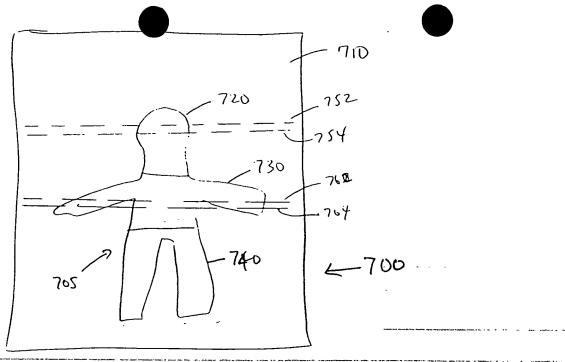


Α

B



The control of the co



Fis 9A

Fig. 9B

, no. rows (= 3)

row1: (color, , n,), (color2, N2), (color3, N3), ... (colorn, Nn)

real: NI, NZ, NZ, NN

row3: N, N2, N3, ..., Nn

Fig.9c (value indicative of volor, run length, offset)

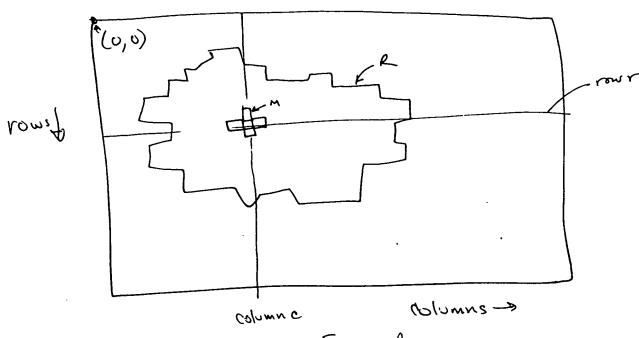
Fig. PD

NO. YOW! (23)

row 1: (cotor, runlingth, offert), (colors, runleythe, offerts), (colorn, runleythe

vow?: (runlingth, offset,), (runlingth, offset,), ... (runlingth, offset,)
vow?: (runlingth, offset,), (runlingth, offset,), ... (runlingth, offset,)

·



F13. 10A

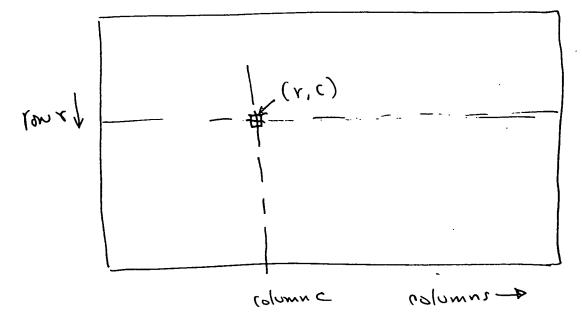
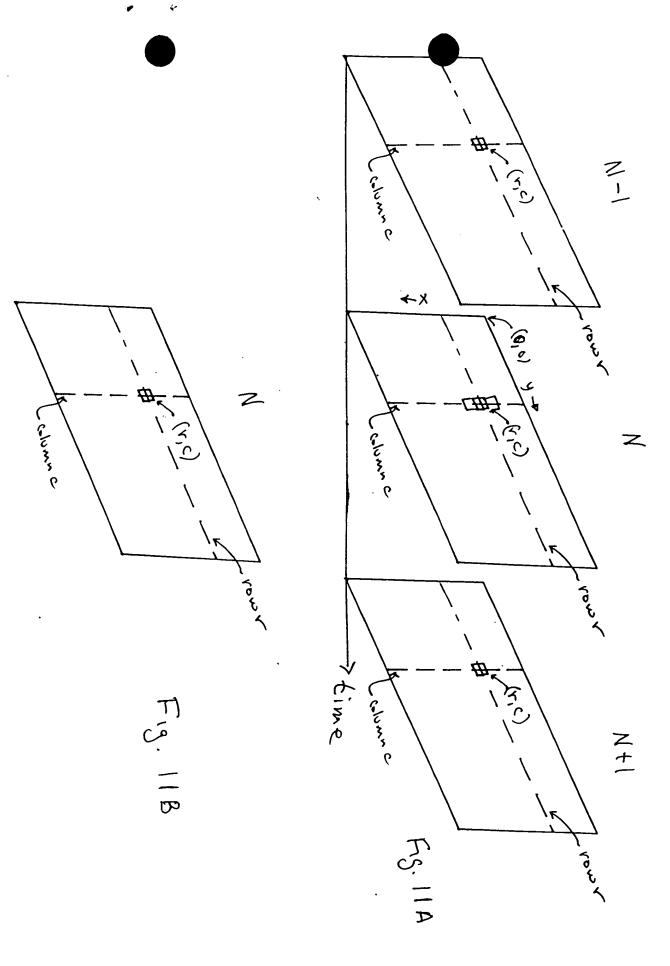
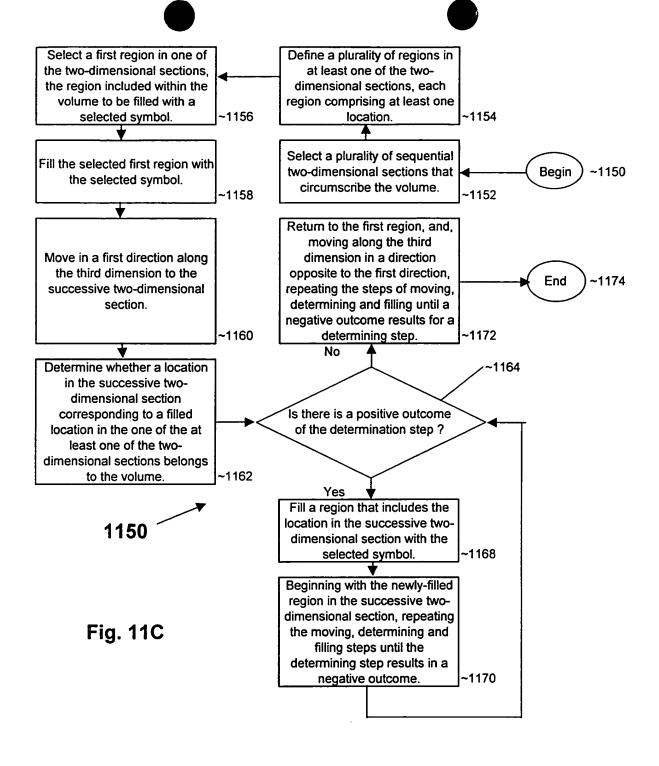
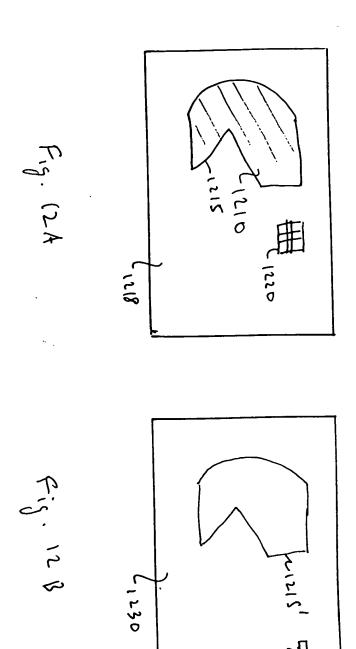


Fig. 10B





동수 4 .



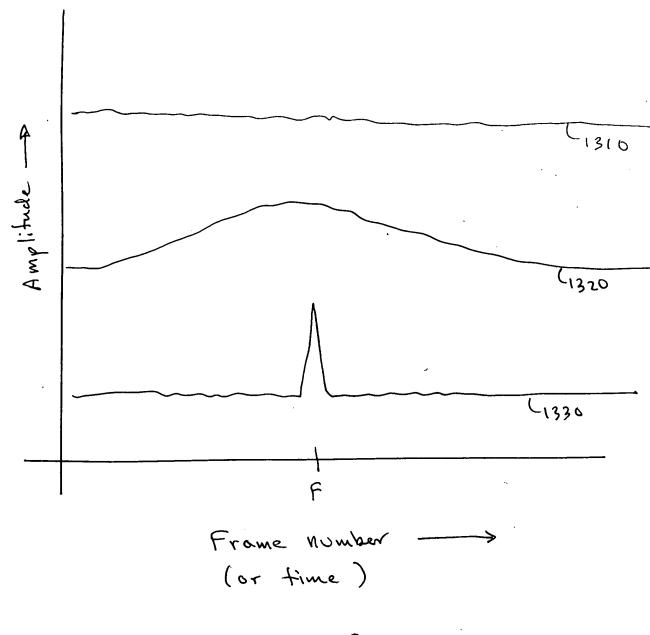


Fig. 13